Plotting with MATLAB

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Week 11

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Plotting with MATLAB

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Before we start...

This week we will see how plotting can be done in MATLAB.

There are a huge variety of types and functionalities for plotting provided by $MATLAB^1$, while we only have limited amount of time.

We focus on the principles of plotting, while discussing only the most representative plot styles.

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How would you draw the graph of y = f(x), without differentiation?

To give you a concrete example, let us try drawing the graph of $f(x) = \sin x$ on the domain $[0, 2\pi]$.

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One would start by sampling several points from the domain, and evaluating f(x) at them.

Using this table, you locate the points where the graph goes through, and then connect them.



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If you sample more points, you get a better plot:

This table allows us to plot the graph as follows:



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Actually, you can do the same thing in MATLAB to plot graphs. There are two ways to do something similar to sampling points from the domain.

The command linspace(a, b, n) generates a vector which contains n equally spaced points, from a to b.

Note that the space between two points is $\frac{b-a}{n-1}$.

The command a : dx : b generates a vector which starts with a, is incremented by dx every element, and contains elements only $\leq b$.

>> $x = 0 : 2 : 6$								
x =								
	0	2	4	6				
>> x	>> $x = 0 : 2 : 5$							
x =								
	0 2 4							

However this method may cause unexpected issues, especially when dx is not an integer. Using linspace is usually safer.

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Now let us plot the graph of $f(x) = \sin x$, by sampling 100 points from the domain $[0, 2\pi]$.

We make a new script, named plot1.m, as:

plot1.m ______ x = linspace(0, 2 * pi, 100); y = sin(x); plot(x, y);

Running the script plot1.m, a figure window appears:



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We can plot multiple functions. One option is as follows.

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Running the script plot2.m, a figure window appears:



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Recall that, from the data points x and y, the command plot(x, y) generates a 'curve' which passes through the points (x_i, y_i) , i = 1, 2, ...

In fact, the data points x and y do not have to be of the form $y_i = f(x_i)$. This suggests a generalization.

For example, a circle cannot be a graph of a function. However, by introducing a parameter t, for example a unit circle can be represented as the set of points

 $\{(\cos t, \sin t) : 0 \le t \le 2\pi\}.$

So let's try this...

circle.m _____

```
t = linspace(0, 2*pi, 101);
x = cos(t);
y = sin(t);
plot(x, y)
axis equal % force axis ratio to be 1:1
```

t	0	$\frac{2\pi}{100}$	$\frac{4\pi}{100}$		2π
$x(=\cos t)$	1	$\cos\left(\frac{2\pi}{100}\right)$	$\cos\left(\frac{4\pi}{100}\right)$	• • •	1
$y(=\sin t)$	0	$\sin\left(\frac{2\pi}{100}\right)$	$\sin\left(\frac{4\pi}{100}\right)$	• • •	0

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The result is, as expected, a circle.



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Using this technique, we can make two-dimensional parametric plots expressed as (x, y) = (f(t), g(t)) for two functions $f, g : \mathbb{R} \to \mathbb{R}$.

There is a three-dimensional counterpart of plot, namely plot3.

For three vectors x, y, and z of the same size, plot3(x, y, z) will draw a curve in \mathbb{R}^3 that passes through the points (x_i, y_i, z_i) , i = 1, 2, ...

Almost everything discussed about plot naturally extends to plot3.

Sometimes you may want to just see where the data points lie on, instead of a graph.

This would especially be the case when you want to visualize data you have collected.

There is a function scatter which is specialized for this task. Let's see what this does.

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Change the plot to scatter...

circle_points.m _____

```
t = linspace(0, 2*pi, 101);
x = cos(t);
y = sin(t);
scatter(x, y)
axis equal % force axis ratio to be 1:1
```

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Now the data points are shown with markers, instead of a curve connecting them.



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In \mathbb{R}^3 , we can also consider plotting a scalar-valued two-variable function of the form z = f(x, y).

Then now, we should sample points from a *two-dimensional* domain, instead of an interval.

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The function meshgrid can be used to make grid points in \mathbb{R}^n .

For now, let us generate grid points in \mathbb{R}^2 .

We use square bracket [X, Y] because meshgrid returns two matrices.

X	=						
		1.0000		1.3333	1.6667	2.0000	
		1.0000		1.3333	1.6667	2.0000	
		1.0000		1.3333	1.6667	2.0000	
Y	=						
		0	0	0	0		
		1	1	1	1		
		2	2	2	2		

After executing mesh_points.m, the outputs X and Y should be as follows.

The vectors $s \in \mathbb{R}^4$ and $t \in \mathbb{R}^3$ specify $4 \times 3 = 12$ gridpoints, and the coordinates of those 12 gridpoints are (X_{ij}, Y_{ij}) .

Let us plot the graph of the function $z = \frac{1}{x^2 + y^2 + 1}$.

surf(X, Y, Z) draws a surface that passes through the points (X_{ij}, Y_{ij}, Z_{ij}) .

surf_plot.m _

```
s = linspace(-1, 1, 100);
t = linspace(-1, 1, 100);
[X, Y] = meshgrid(s, t);
Z = 1 ./ (X.^2 + Y.^2 + 1);
surf(X, Y, Z)
```

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Note: by dragging the plot around, you can change the point of view.



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mesh(X, Y, Z) draws a 'wireframe' version of the surface that passes through the points (X_{ij}, Y_{ij}, Z_{ij}) .

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Now the figure only shows the 'frame' of the surface.



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Vector fields are, simply put, functions from \mathbb{R}^n to \mathbb{R}^n .

Recall that vectors in \mathbb{R}^2 and \mathbb{R}^3 can be visualized by an arrow.

So, given a vector field $\mathbf{F}: \mathbb{R}^2 \to \mathbb{R}^2$ or $\mathbb{R}^3 \to \mathbb{R}^3$, we can visualize it by:

- (i) sample points from the domain,
- (ii) for each sample point \mathbf{x} , draw an arrow corresponding to the vector $\mathbf{F}(\mathbf{x})$ with the initial point at \mathbf{x} .

quiver(x, y, u, v) plots the vector field $(u, v) = \mathbf{F}(x, y)$ with arrows.

Let us plot the graph of the vector field $(u, v) = \mathbf{F}(x, y) = (-y, x)$.

The arrows are scaled so that they do not overlap.



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quiver3(x, y, z, u, v, w) plots the vector field $(u, v, w) = \mathbf{F}(x, y, z)$.

Let us visualize the *inverse square law* by plotting the vector field

$$(u, v, w) = \left(-\frac{x}{x^2 + y^2 + z^2}, -\frac{y}{x^2 + y^2 + z^2}, -\frac{z}{x^2 + y^2 + z^2}\right).$$

inverse_square_field.m ____

r = linspace(-1, 1, 7); s = linspace(-1, 1, 7); t = linspace(-1, 1, 7); [x, y, z] = meshgrid(r, s, t); u = -x ./ (x.^2 + y.^2 + z.^2); v = -y ./ (x.^2 + y.^2 + z.^2); w = -z ./ (x.^2 + y.^2 + z.^2); quiver3(x, y, z, u, v, w)

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Plotting Vector Fields



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Thank you!

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